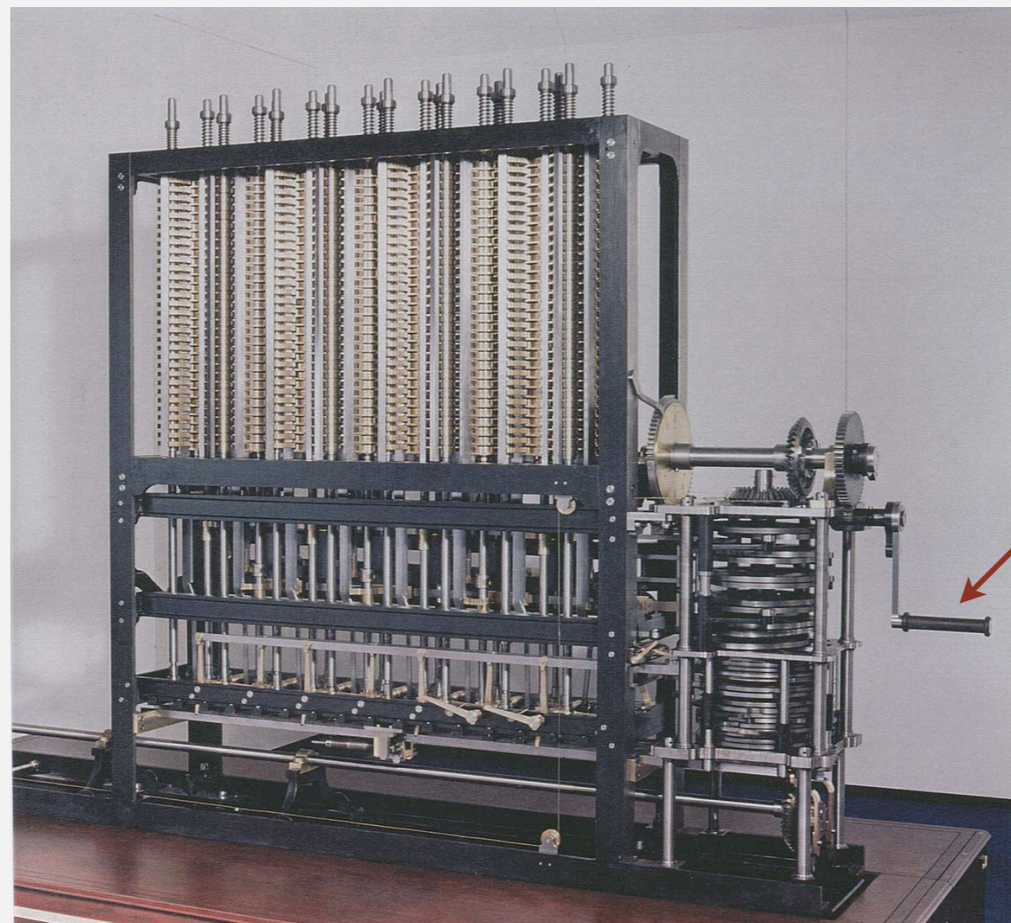
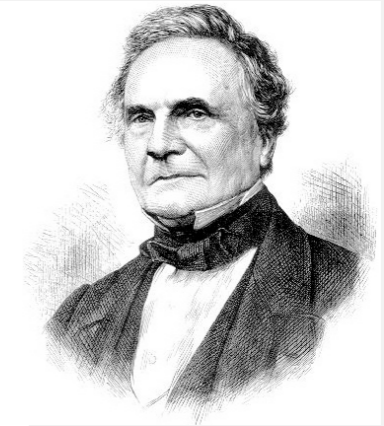


Running time

“ As soon as an Analytic Engine exists, it will necessarily guide the future course of the science. Whenever any result is sought by its aid, the question will arise—By what course of calculation can these results be arrived at by the machine in the shortest time? ” — Charles Babbage (1864)



how many times do you have to turn the crank?

Analytic Engine

Cast of characters



Programmer needs to develop a working solution.



Student might play any or all of these roles someday.



Client wants to solve problem efficiently.



Theoretician wants to understand.

Reasons to analyze algorithms

Predict performance.

Compare algorithms.

Provide guarantees.

Understand theoretical basis.

this course (COS 226)

theory of algorithms (COS 423)

Primary practical reason: avoid performance bugs.



client gets poor performance because programmer did not understand performance characteristics



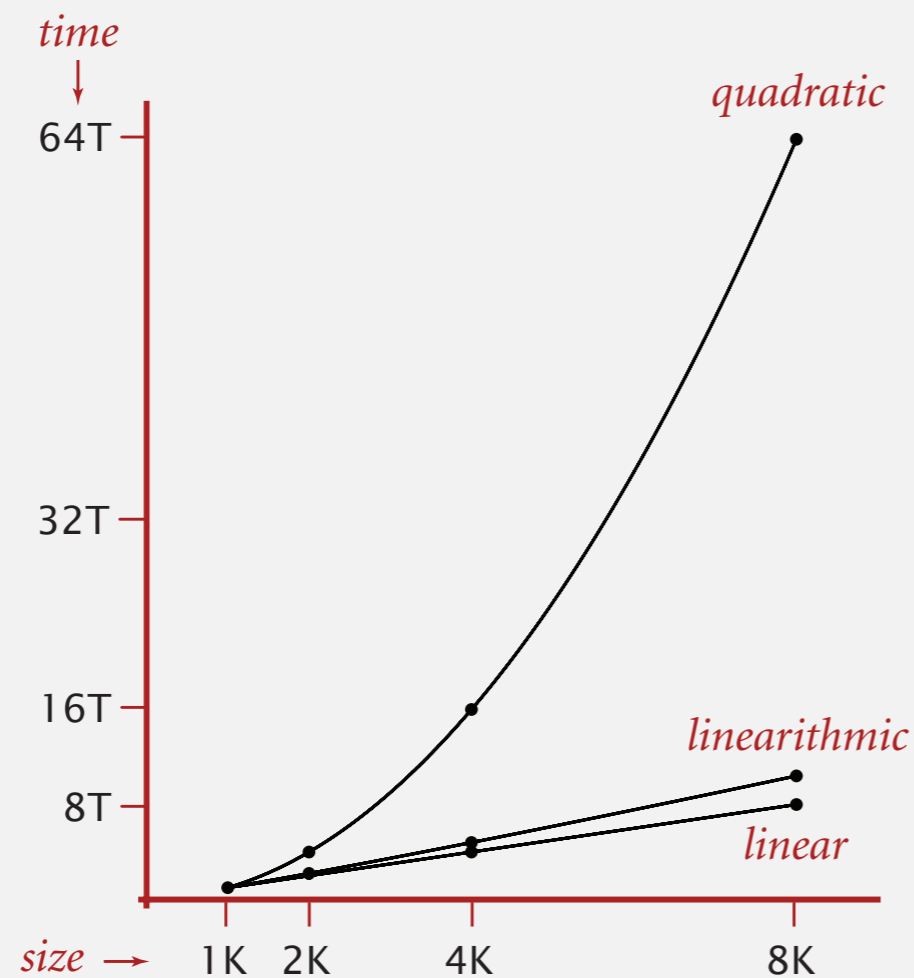
Some algorithmic successes

Discrete Fourier transform.

- Break down waveform of N samples into periodic components.
- Applications: DVD, JPEG, MRI, astrophysics,
- Brute force: N^2 steps.
- FFT algorithm: $N \log N$ steps, **enables new technology.**



Friedrich Gauss
1805



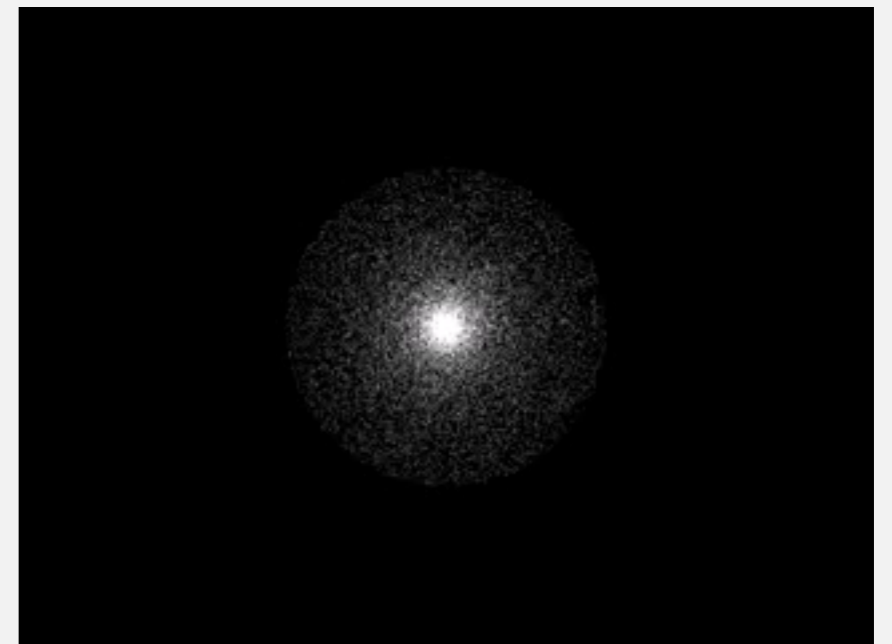
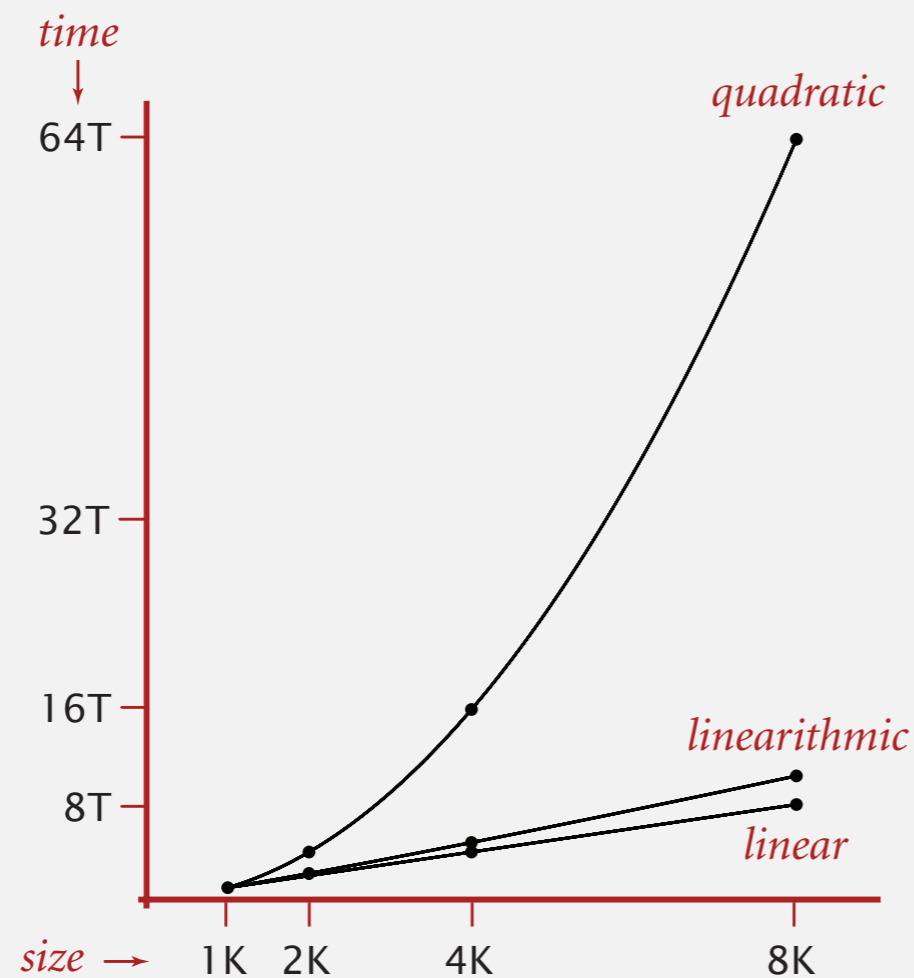
Some algorithmic successes

N-body simulation.

- Simulate gravitational interactions among N bodies.
- Brute force: N^2 steps.
- Barnes-Hut algorithm: $N \log N$ steps, **enables new research.**



Andrew Appel
PU '81



The challenge

Q. Will my program be able to solve a large practical input?

Why is my program so slow ?

Why does it run out of memory ?



Insight. [Knuth 1970s] Use **scientific method** to understand performance.

Scientific method applied to analysis of algorithms

A framework for predicting performance and comparing algorithms.

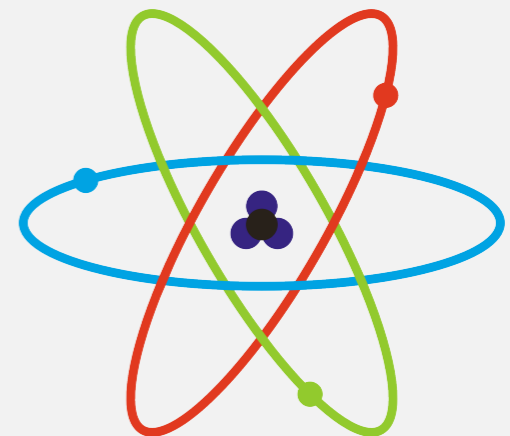
Scientific method.

- **Observe** some feature of the natural world.
- **Hypothesize** a model that is consistent with the observations.
- **Predict** events using the hypothesis.
- **Verify** the predictions by making further observations.
- **Validate** by repeating until the hypothesis and observations agree.

Principles.

- Experiments must be **reproducible**.
- Hypotheses must be **falsifiable**.

Feature of the natural world. Computer itself.



3-SUM: brute-force algorithm

```
public class ThreeSum
{
    public static int count(int[] a)
    {
        int N = a.length;
        int count = 0;
        for (int i = 0; i < N; i++)
            for (int j = i+1; j < N; j++)
                for (int k = j+1; k < N; k++)
                    if (a[i] + a[j] + a[k] == 0)
                        count++;
        return count;
    }

    public static void main(String[] args)
    {
        In in = new In(args[0]);
        int[] a = in.readAllInts();
        StdOut.println(count(a));
    }
}
```

← check each triple
← for simplicity, ignore integer overflow

Measuring the running time

Q. How to time a program?

A. Automatic.

```
public class Stopwatch (part of stdlib.jar)
```

```
    Stopwatch() create a new stopwatch
```

```
    double elapsedTime() time since creation (in seconds)
```

```
public static void main(String[] args)
{
    In in = new In(args[0]);
    int[] a = in.readAllInts();
    Stopwatch stopwatch = new Stopwatch();
    StdOut.println(ThreeSum.count(a));
    double time = stopwatch.elapsedTime();
    StdOut.println("elapsed time " + time);
}
```

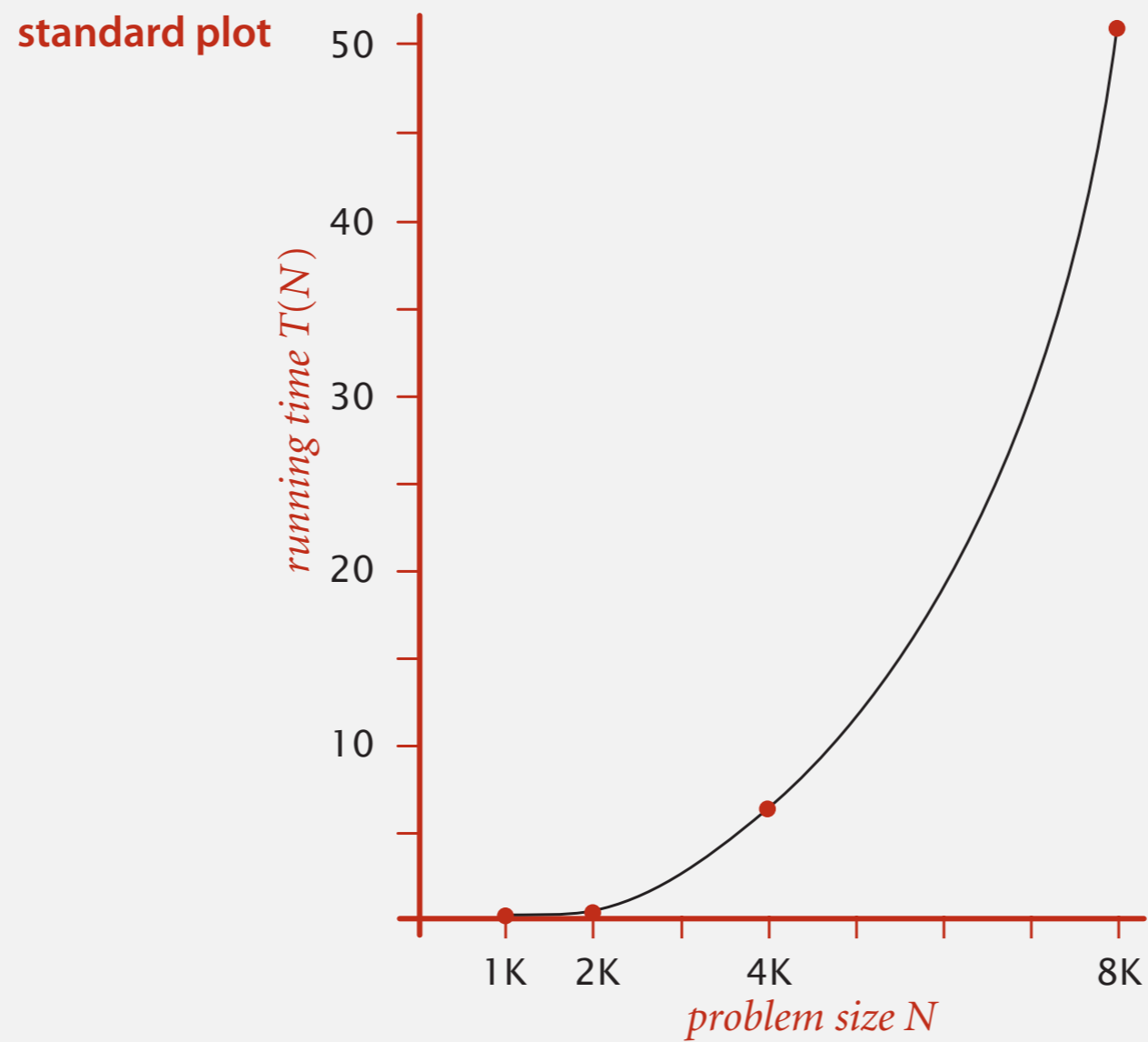
Empirical analysis

Run the program for various input sizes and measure running time.

| N | time (seconds) † |
|--------|------------------|
| 250 | 0.0 |
| 500 | 0.0 |
| 1,000 | 0.1 |
| 2,000 | 0.8 |
| 4,000 | 6.4 |
| 8,000 | 51.1 |
| 16,000 | ? |

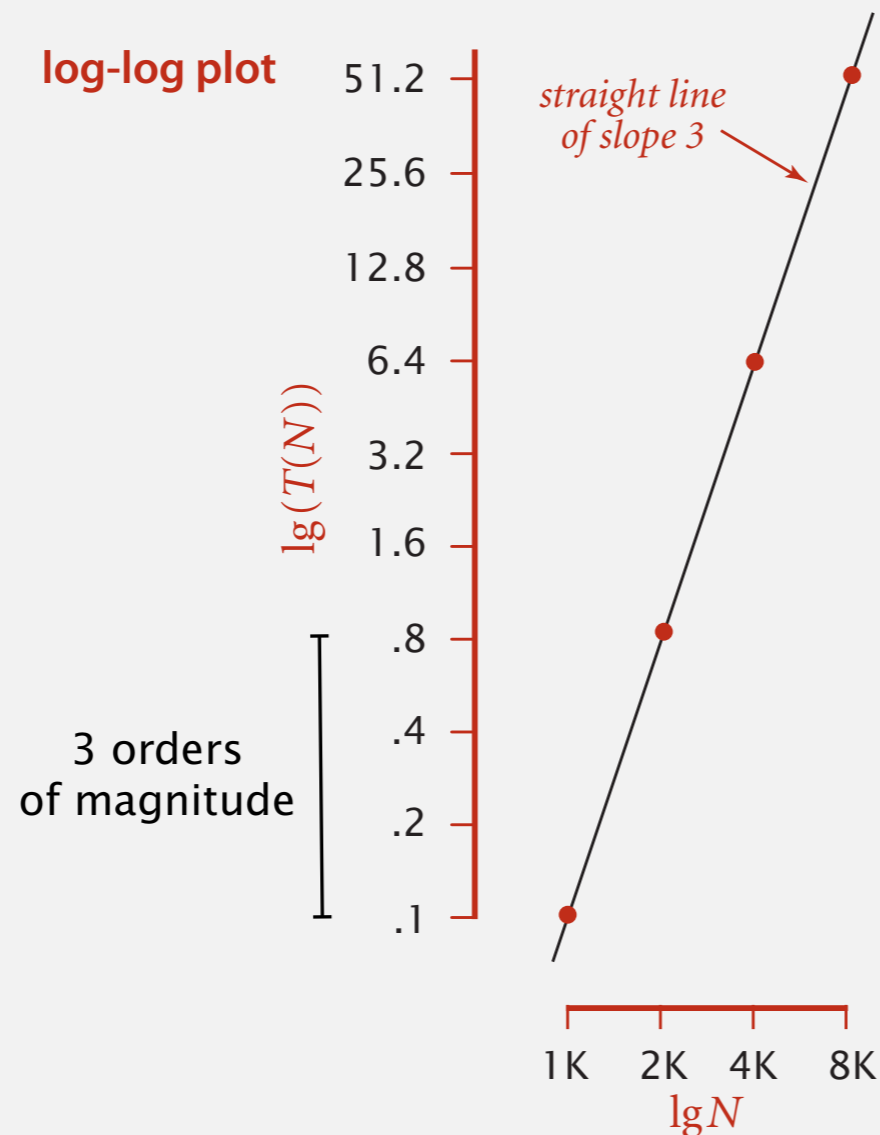
Data analysis

Standard plot. Plot running time $T(N)$ vs. input size N .



Data analysis

Log-log plot. Plot running time $T(N)$ vs. input size N using **log-log scale**.



$$\lg(T(N)) = b \lg N + c$$

$$b = 2.999$$

$$c = -33.2103$$

$$T(N) = a N^b, \text{ where } a = 2^c$$

Regression. Fit straight line through data points: $a N^b$.

Hypothesis. The running time is about $1.006 \times 10^{-10} \times N^{2.999}$ seconds.


power law

slope

Prediction and validation

Hypothesis. The running time is about $1.006 \times 10^{-10} \times N^{2.999}$ seconds.

"order of growth" of running time is about N^3 [stay tuned]



Predictions.

- 51.0 seconds for $N = 8,000$.
- 408.1 seconds for $N = 16,000$.

Observations.

| N | time (seconds) † |
|--------|------------------|
| 8,000 | 51.1 |
| 8,000 | 51.0 |
| 8,000 | 51.1 |
| 16,000 | 410.8 |

validates hypothesis!

Doubling hypothesis

Doubling hypothesis. Quick way to estimate b in a power-law relationship.

Run program, **doubling** the size of the input.

| N | time (seconds) † | ratio | lg ratio |
|-------|------------------|-------|----------|
| 250 | 0.0 | | – |
| 500 | 0.0 | 4.8 | 2.3 |
| 1,000 | 0.1 | 6.9 | 2.8 |
| 2,000 | 0.8 | 7.7 | 2.9 |
| 4,000 | 6.4 | 8.0 | 3.0 |
| 8,000 | 51.1 | 8.0 | 3.0 |

$$\begin{aligned}\frac{T(2N)}{T(N)} &= \frac{a(2N)^b}{aN^b} \\ &= 2^b\end{aligned}$$

← $\lg(6.4 / 0.8) = 3.0$

↑
seems to converge to a constant $b \approx 3$

Hypothesis. Running time is about $a N^b$ with $b = \lg \text{ratio}$.

Caveat. Cannot identify logarithmic factors with doubling hypothesis.

Experimental algorithmics

System independent effects.

- Algorithm.
 - Input data.
- } determines exponent
in power law

System dependent effects.

- Hardware: CPU, memory, cache, ...
- Software: compiler, interpreter, garbage collector, ...
- System: operating system, network, other apps, ...

} determines constant
in power law

Bad news. Difficult to get precise measurements.

Good news. Much easier and cheaper than other sciences.

↖ e.g., can run huge number of experiments

Cost of basic operations

Challenge. How to estimate constants.

| operation | example | nanoseconds † |
|-------------------------|-------------------------------|---------------|
| integer add | $a + b$ | 2.1 |
| integer multiply | $a * b$ | 2.4 |
| integer divide | a / b | 5.4 |
| floating-point add | $a + b$ | 4.6 |
| floating-point multiply | $a * b$ | 4.2 |
| floating-point divide | a / b | 13.5 |
| sine | <code>Math.sin(theta)</code> | 91.3 |
| arctangent | <code>Math.atan2(y, x)</code> | 129.0 |
| ... | ... | ... |

† Running OS X on Macbook Pro 2.2GHz with 2GB RAM

Cost of basic operations

Observation. Most primitive operations take constant time.

| operation | example | nanoseconds † |
|----------------------|----------------------------|---------------|
| variable declaration | <code>int a</code> | c_1 |
| assignment statement | <code>a = b</code> | c_2 |
| integer compare | <code>a < b</code> | c_3 |
| array element access | <code>a[i]</code> | c_4 |
| array length | <code>a.length</code> | c_5 |
| 1D array allocation | <code>new int[N]</code> | $c_6 N$ |
| 2D array allocation | <code>new int[N][N]</code> | $c_7 N^2$ |

Caveat. Non-primitive operations often take more than constant time.

 novice mistake: abusive string concatenation

Simplifying the calculations

*“ It is convenient to have a **measure of the amount of work involved in a computing process**, even though it be a very **crude one**. We may count up the number of times that various elementary operations are applied in the whole process and then given them various weights. We might, for instance, count the number of additions, subtractions, multiplications, divisions, recording of numbers, and extractions of figures from tables. In the case of computing with matrices most of the work consists of multiplications and writing down numbers, and we shall therefore only attempt to count the number of **multiplications and recordings**. ” — Alan Turing*

ROUNDING-OFF ERRORS IN MATRIX PROCESSES

By A. M. TURING

(National Physical Laboratory, Teddington, Middlesex)

[Received 4 November 1947]

SUMMARY

A number of methods of solving sets of linear equations and inverting matrices are discussed. The theory of the rounding-off errors involved is investigated for some of the methods. In all cases examined, including the well-known ‘Gauss elimination process’, it is found that the errors are normally quite moderate: no exponential build-up need occur.



Common order-of-growth classifications


Definition. If $f(N) \sim c g(N)$ for some constant $c > 0$, then the **order of growth** of $f(N)$ is $g(N)$.

- Ignores leading coefficient.
- Ignores lower-order terms.

Ex. The order of growth of the **running time** of this code is N^3 .

```
int count = 0;
for (int i = 0; i < N; i++)
    for (int j = i+1; j < N; j++)
        for (int k = j+1; k < N; k++)
            if (a[i] + a[j] + a[k] == 0)
                count++;
```

Typical usage. With running times.

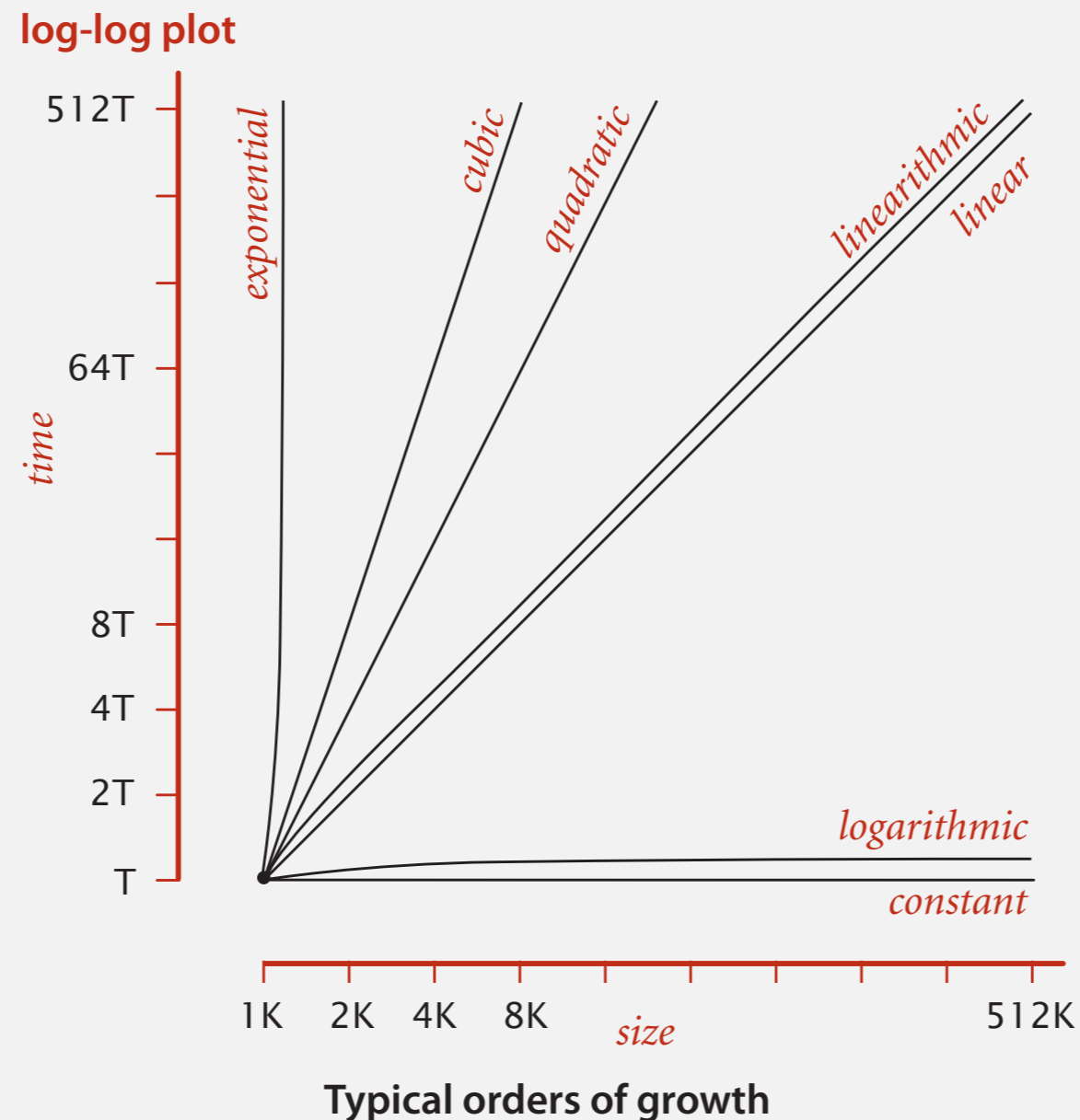
 where leading coefficient
depends on machine, compiler, JVM, ...

Common order-of-growth classifications

Good news. The set of functions

1, $\log N$, N , $N \log N$, N^2 , N^3 , and 2^N

suffices to describe the order of growth of most common algorithms.



Common order-of-growth classifications

| order of growth | name | typical code framework | description | example | $T(2N) / T(N)$ |
|-----------------|---------------------|---|--------------------|-------------------|----------------|
| 1 | constant | <code>a = b + c;</code> | statement | add two numbers | 1 |
| $\log N$ | logarithmic | <pre>while (N > 1) { N = N / 2; ... }</pre> | divide in half | binary search | ~ 1 |
| N | linear | <pre>for (int i = 0; i < N; i++) { ... }</pre> | loop | find the maximum | 2 |
| $N \log N$ | linearithmic | [see mergesort lecture] | divide and conquer | mergesort | ~ 2 |
| N^2 | quadratic | <pre>for (int i = 0; i < N; i++) for (int j = 0; j < N; j++) { ... }</pre> | double loop | check all pairs | 4 |
| N^3 | cubic | <pre>for (int i = 0; i < N; i++) for (int j = 0; j < N; j++) for (int k = 0; k < N; k++) { ... }</pre> | triple loop | check all triples | 8 |
| 2^N | exponential | [see combinatorial search lecture] | exhaustive search | check all subsets | $T(N)$ |

Binary search demo

Goal. Given a sorted array and a key, find index of the key in the array?

Binary search. Compare key against middle entry.

- Too small, go left.
- Too big, go right.
- Equal, found.



successful search for 33

| | | | | | | | | | | | | | | |
|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| 6 | 13 | 14 | 25 | 33 | 43 | 51 | 53 | 64 | 72 | 84 | 93 | 95 | 96 | 97 |
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 |
| ↑ | | | | | | | | | | | | | | ↑ |
| lo | | | | | | | | | | | | | | hi |

Comparing programs

Hypothesis. The sorting-based $N^2 \log N$ algorithm for 3-SUM is significantly faster in practice than the brute-force N^3 algorithm.

| N | time (seconds) |
|-------|----------------|
| 1,000 | 0.1 |
| 2,000 | 0.8 |
| 4,000 | 6.4 |
| 8,000 | 51.1 |

ThreeSum.java

| N | time (seconds) |
|--------|----------------|
| 1,000 | 0.14 |
| 2,000 | 0.18 |
| 4,000 | 0.34 |
| 8,000 | 0.96 |
| 16,000 | 3.67 |
| 32,000 | 14.88 |
| 64,000 | 59.16 |

ThreeSumDeluxe.java

Guiding principle. Typically, better order of growth \Rightarrow faster in practice.

Types of analyses

Best case. Lower bound on cost.

- Determined by “easiest” input.
- Provides a goal for all inputs.

Worst case. Upper bound on cost.

- Determined by “most difficult” input.
- Provides a guarantee for all inputs.

Average case. Expected cost for random input.

- Need a model for “random” input.
- Provides a way to predict performance.

this course

Ex 1. Array accesses for brute-force 3-SUM.

Best: $\sim \frac{1}{2} N^3$

Average: $\sim \frac{1}{2} N^3$

Worst: $\sim \frac{1}{2} N^3$

Ex 2. Compares for binary search.

Best: ~ 1

Average: $\sim \lg N$

Worst: $\sim \lg N$

Theory of algorithms

Goals.

- Establish “difficulty” of a problem.
- Develop “optimal” algorithms.

Approach.

- Suppress details in analysis: analyze “to within a constant factor.”
- Eliminate variability in input model: focus on the worst case.

Upper bound. Performance guarantee of algorithm for any input.

Lower bound. Proof that no algorithm can do better.

Optimal algorithm. Lower bound = upper bound (to within a constant factor).

Commonly-used notations in the theory of algorithms

| notation | provides | example | shorthand for | used to |
|------------------|----------------------------|---------------|---|----------------------|
| Big Theta | asymptotic order of growth | $\Theta(N^2)$ | $\frac{1}{2} N^2$ $10 N^2$ $5 N^2 + 22 N \log N + 3N$ \vdots | classify algorithms |
| Big Oh | $\Theta(N^2)$ and smaller | $O(N^2)$ | $10 N^2$ $100 N$ $22 N \log N + 3 N$ \vdots | develop upper bounds |
| Big Omega | $\Theta(N^2)$ and larger | $\Omega(N^2)$ | $\frac{1}{2} N^2$ N^5 $N^3 + 22 N \log N + 3 N$ \vdots | develop lower bounds |

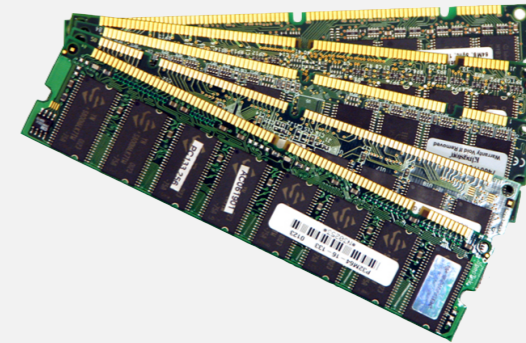
Basics

Bit. 0 or 1.
Byte. 8 bits.
Megabyte (MB). 1 million or 2^{20} bytes.
Gigabyte (GB). 1 billion or 2^{30} bytes.

NIST



most computer scientists



64-bit machine. We assume a 64-bit machine with 8-byte pointers.

- Can address more memory.
- Pointers use more space.

some JVMs "compress" ordinary object pointers to 4 bytes to avoid this cost



Typical memory usage for primitive types and arrays

| type | bytes |
|---------|-------|
| boolean | 1 |
| byte | 1 |
| char | 2 |
| int | 4 |
| float | 4 |
| long | 8 |
| double | 8 |

primitive types

| type | bytes |
|----------|-----------|
| char[] | $2N + 24$ |
| int[] | $4N + 24$ |
| double[] | $8N + 24$ |

one-dimensional arrays

| type | bytes |
|------------|------------|
| char[][] | $\sim 2MN$ |
| int[][] | $\sim 4MN$ |
| double[][] | $\sim 8MN$ |

two-dimensional arrays

Typical memory usage for objects in Java

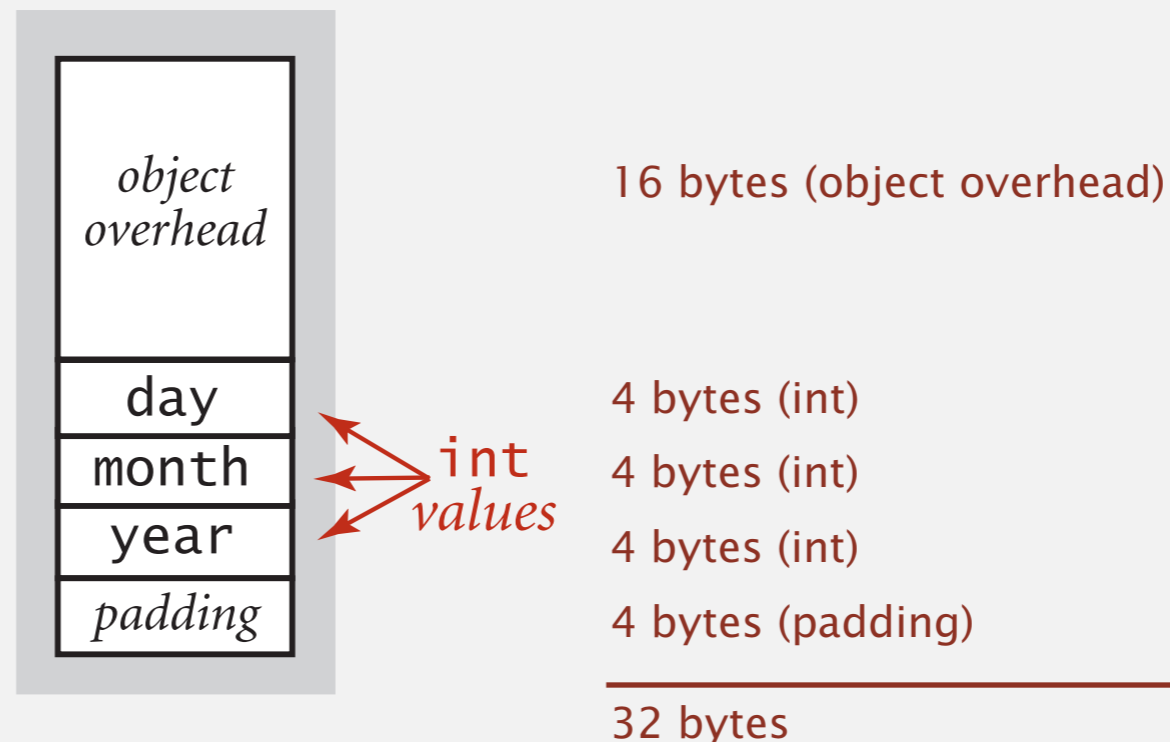
Object overhead. 16 bytes.

Reference. 8 bytes.

Padding. Each object uses a multiple of 8 bytes.

Ex 1. A Date object uses 32 bytes of memory.

```
public class Date
{
    private int day;
    private int month;
    private int year;
    ...
}
```




Typical memory usage summary

Total memory usage for a data type value:

- Primitive type: 4 bytes for `int`, 8 bytes for `double`, ...
- Object reference: 8 bytes.
- Array: 24 bytes + memory for each array entry.
- Object: 16 bytes + memory for each instance variable.
- Padding: round up to multiple of 8 bytes.

+ 8 extra bytes per inner class object
(for reference to enclosing class)



Shallow memory usage: Don't count referenced objects.

Deep memory usage: If array entry or instance variable is a reference, count memory (recursively) for referenced object.

Example

Q. How much memory does `WeightedQuickUnionUF` use as a function of N ?
Use tilde notation to simplify your answer.

```
public class WeightedQuickUnionUF
```

```
{
```

```
    private int[] id;
```

```
    private int[] sz;
```

```
    private int count;
```

```
    public WeightedQuickUnionUF(int N)
```

```
{
```

```
        id = new int[N];
```

```
        sz = new int[N];
```

```
        for (int i = 0; i < N; i++) id[i] = i;
```

```
        for (int i = 0; i < N; i++) sz[i] = 1;
```

```
    }
```

```
    ...
```

```
}
```

← 16 bytes
(object overhead)

← 8 + (4N + 24) bytes each
(reference + int[] array)

← 4 bytes (int)

← 4 bytes (padding)

8N + 88 bytes

A. $8N + 88 \sim 8N$ bytes.

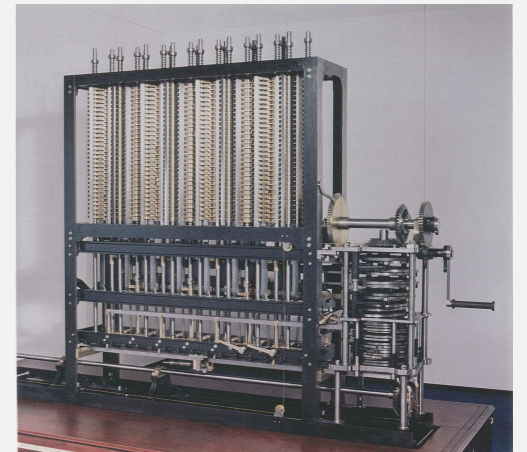
Turning the crank: summary

Empirical analysis.

- Execute program to perform experiments.
- Assume power law and formulate a hypothesis for running time.
- Model enables us to **make predictions**.

Mathematical analysis.

- Analyze algorithm to count frequency of operations.
- Use tilde notation to simplify analysis.
- Model enables us to **explain behavior**.



Scientific method.

- Mathematical model is independent of a particular system; applies to machines not yet built.
- Empirical analysis is necessary to validate mathematical models and to make predictions.